

**ΥΠΟΛΟΓΙΣΜΟΣ ΠΕΔΙΩΝ ΣΕ ΑΠΛΕΣ
ΜΑΓΝΗΤΟ- ΚΑΙ ΕΛΕΚΤΡΟ- ΣΤΑΤΙΚΕΣ ΠΕΡΙΠΤΩΣΕΙΣ**

$$\phi_e(z; z_\sigma) = -\frac{\sigma_{tot}}{2\epsilon_0}|z - z_\sigma|, \quad d\phi_e(z; z_\sigma) = -\frac{\rho_{tot}(z_\sigma)dz_\sigma}{2\epsilon_0}|z - z_\sigma|$$

$$\phi_e(r_T) = -\frac{\lambda_{tot}}{2\pi\epsilon_0} \ln\left(\frac{r_T}{r_{T0}}\right), \quad d\phi_e(r_T; x_\lambda, y_\lambda) = -\frac{\rho_{tot}(x_\lambda, y_\lambda)dx_\lambda dy_\lambda}{2\pi\epsilon_0} \ln\left(\frac{r_T}{r_{T0}}\right)$$

$$\vec{E} = -\nabla\phi_e, \quad \rho_{tot} = \rho_u + \rho_p, \quad \sigma_{tot} = \sigma_u + \sigma_p, \quad \lambda_{tot} = \lambda_u + \lambda_p$$

$$A_y(z; z_K) = -\frac{\mu_0 K_{u,y}}{2}|z - z_K|, \quad dA_y(z; z_K) = -\frac{\mu_0 J_{u,y}(z_K)dz_K}{2}|z - z_K|$$

$$A_z(r_T) = -\frac{\mu_0 I_u}{2\pi} \ln\left(\frac{r_T}{r_{T0}}\right), \quad dA_z(r_T; x_l, y_l) = -\frac{\mu_0 J_{u,z}(x_l, y_l)dx_l dy_l}{2\pi} \ln\left(\frac{r_T}{r_{T0}}\right)$$

$$\vec{H} = \frac{\nabla \times \vec{A}}{\mu_0}$$