# Simplified fragility-based risk analysis for impulse governed blast loading scenarios

3	Pierluigi Olmati <sup>a</sup> , Francesco Petrini <sup>b</sup> , Dimitrios Vamvatsikos <sup>c</sup> , Charis Gantes <sup>c</sup>
4	<sup>a</sup> Tokyo Polytechnic University, Atsugi, Kanagawa, Japan, Email: pierluigi.olmati@gmail.com
5	<sup>b</sup> Sapienza University of Rome, School of Civil and Industrial Engineering, Rome, Italy,

<sup>c</sup> National Technical University of Athens, School of Civil Engineering, Athens, Greece

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# 10 Abstract

Blast-loaded structures are presently assessed and designed following a deterministic approach, 11 12 where only a set of structural analyses under worst-case design scenarios are carried out in order to 13 verify each limit state. As a rational alternative, a conditional probabilistic approach is introduced to 14 offer comprehensive risk assessment and to allow the design with user-defined confidence in 15 meeting performance targets in view of uncertainties. To simplify the probabilistic consideration of 16 the uncertain parameters, the determination of the blast hazard and the structural response are 17 decoupled into the evaluation of blast hazard curves and structural fragilities curves, respectively, 18 by introducing a single conditioning intensity measure. This is chosen to be the impulse density, 19 shown to be sufficient for impulse-governed scenarios, achieving a reduction of the computational 20 effort by several orders of magnitude without introducing bias. Furthermore a problem-specific 21 safety factor formulation is introduced to incorporate the influence of uncertainties in a simple manner, akin to current engineering practice. As a proof-of-concept test, a steel built-up blast 22 23 resistant door is subjected to an accidental detonation of mortar rounds in a military facility. The 24 equivalent single degree of freedom model is adopted in order to conduct the structural analyses, 25 while detailed finite element analyses are carried out for validation. Finally, the conditional 26 approach risk analysis on the steel door is compared against the results obtained through the 27 comprehensive (probabilistic) unconditional approach, showing the validity of both the proposed 28 intensity measure and safety factor formulation.

# 29 **1 Introduction**

As for any structural problem, in order to assess the response of structures subjected to a detonation
the following tasks must be achieved:

- a) hazard (blast) analysis [1, 2],
- b) structural demand assessment (i.e. structural analysis) [2],
- c) structure/component capacity assessment [2],
- d) safety assessment (i.e., comparison of demand and capacity) [3].

Usually the execution of all of the above steps is conducted in a deterministic rather than a
probabilistic way. At the scale of the structural system the global response can be assessed by
considering pertinent damage scenarios [4, 5] while at the scale of the single structural element
detailed numerical models are employed for the correct prediction of both blast demand [6 - 7] and
damage pattern of the structural element [8].

41 While, generally, the deterministic approach is preferred in order to design structures under blast 42 loads, a number of works can be useful in order to calibrate probabilistic models and bound the 43 uncertainties affecting the design of blast resistant structures. Stewart and Netherton [9] studied two 44 types of window glazing system and investigated the crucial issue of selecting an appropriate 45 intensity measure for computing the fragility curves for blast loaded structures. The fragility curves 46 are developed as a function of two different intensity measures (the explosive weight and the stand-47 off distance) and several fragility curves are computed for specific cases of study. Netherton and 48 Stewart [10] investigated the accuracy of the blast loading prediction model, concluding that the 49 overall risk is sensitive to uncertainties of the blast load model. An example regarding the 50 complexity of the blast load modeling is shown in the work of Ballantyne et al. [6] where the 51 clearing effect for finite width surfaces is investigated. In the study of Wu et al. [11] a series of 52 different kinds of concrete slabs are tested in order to both compare their blast resistance and 53 evaluate the uncertainty affecting the pressure estimation procedures provided in the Unified 54 Facilities Criteria (UFC) 3-340-02 [2] manual. Chang and Young [12] used Monte Carlo simulations in order to estimate the probability of failure for windows subjected to blast load 55 induced by a vehicle bomb. Low and Hao [13] presented results of a parametric investigation on the 56 57 reliability of reinforced concrete slabs under blast loading in order to establish appropriate 58 probabilistic distributions of the resistance parameters. Olmati et al. [14] carried out fragility 59 analyses for the performance-based design of cladding wall panels subjected to blast load by

adopting the scaled distance as intensity measure, and presented a discussion about the effectivenessof this choice.

62 The difference between deterministic and probabilistic approach is that in the first case only one 63 blast load scenario is considered in order to define the hazard, usually taken to be representative of the worst case. Then, a single structural model realization, typically incorporating average or 64 65 characteristic material properties, is analyzed to obtain the corresponding Demand (D) value. Similarly the Capacity (C) is assumed to be a single value describing an upper threshold in the 66 67 response parameter of interest (e.g. rotation or strain), which when exceeded determines the violation of the limit state. The safety comparison is performed through the well-known equation 68 69 *C*>*D*; as a consequence, the result is a binary "safe" or "unsafe" answer.

Conceptually, the probabilistic approach can be considered to be a repetition of the deterministic assessment over many (ideally all) possible scenarios. Then, the safety assessment becomes an evaluation of the probability that the demand exceeds the capacity, formally P(C < D), also known as the probability of exceedance of the limit state that is tied to the capacity. For example, if one considers  $N_b$  equally probable blast loadings,  $N_s$  equally probable realizations of the structure and  $N_c$  equally probable capacity values, then P(C < D) is the fraction of the  $N_b \cdot N_s \cdot N_c$  scenarios where the demand exceeds the capacity.

77 Both the advantages and disadvantages of using the probabilistic approach are well-discussed in the 78 literature [15 - 17]. They mainly revolve around the complexity of applying a probabilistic analysis 79 versus the additional insight, reliability and often economy offered when one takes into account all 80 pertinent uncertainties. The emergence of performance-based engineering and present abundance of 81 computational resources have allowed the adoption of probabilistic methods in many fields of the 82 civil engineering [18 - 23], a trend that is, nowadays, also moving into blast [9, 10, 14, 24]. In view 83 of such advancements, a streamlined method for probabilistic performance-based blast analysis is proposed here for impulse-governed loading of first-mode-dominated structures. Essentially it 84 85 confers all of its advantages while removing its perceived complexity by having a low 86 computational footprint and closed-form solutions for safety assessment.

#### **2 Probabilistic basis for performance assessment**

Assessing the probability of exceedance for any limit state of interest, P(C < D), can be achieved by several procedures that can be broadly categorized in two classes: the unconditional (UA) and conditional (CA) approach. In the unconditional approach, samples of blast scenarios, model

91 realizations, and potential capacity values are generated, then combined in order to determine 92 P(C < D) by a single Monte Carlo simulation. The unconditional approach is exactly the generation of the  $N_b \cdot N_s \cdot N_c$  scenarios described earlier, from which the fraction that violates (exceeds) the limit 93 94 state is evaluated. The main disadvantage of the unconditional approach is the need for performing 95  $N_b N_s$  structural analyses, if the value of capacity is assumed not to influence the structural response, or  $N_b \cdot N_s \cdot N_c$  otherwise. This has led to the adoption of the so-called conditional approach, widely 96 97 used in earthquake engineering [25, 26]. Therein, an interface variable, called intensity measure (IM), is introduced to be able to fully represent the characteristics of the hazard in a single scalar (or 98 99 rarely vector) variable. Formally, IM needs to be "sufficient" [27]. Then, hazard analysis needs to 100 assess the distribution of *IM* arising from the potential blast scenarios, while structural analysis is 101 reduced to computing the distribution of structural response conditioned on the value of the (scalar) 102 IM.

103 A blast scenario depends on multiple parameters (stand-off distance, charge weight, height of the 104 detonation, presence of barriers, etc.). Conversely, an unconditional approach would involve the 105 determination of structural response over the vector of hazard parameters, leading to a large number 106 of blast scenario realizations  $N_b$  and corresponding structural analyses. By introducing a scalar IM, 107 the conditional approach effectively reduces the structural analysis effort by several orders of magnitude. Perhaps the only downside is that the probability of exceedance of the limit state is no 108 109 longer a simple fraction but instead necessitates the integration through the application of the total probability theorem: 110

$$P(C < D) = \int_{0}^{+\infty} P(C < D \mid IM) f(IM) \,\partial IM \tag{1}$$

111 The target of structural analysis now becomes the assessment of the conditional probability of exceeding a limit state, P(C < D | IM), the so-called limit state fragility curve or function [28]. 112 113 P(C < D | IM) is determined for a range of IM, ideally from a value of IM=0 to a value that causes the probability of exceedance to become 1, essentially guaranteeing failure. f(IM) is the probability 114 115 density function (PDF) of encountering a given IM value and its determination is the target of the blast hazard assessment. Thus, the problem is efficiently divided in two parts with the benefit that 116 117 the complete structural characterization, achieved by the fragility curve, can be used for any blast scenario (different charge weights, stand-offs, etc.). As both the demand D and the capacity C are 118 119 random variables, the actual evaluation of the probability of exceedance can become more complex 120 than Eq. (1) implies. Following simplifying assumptions and methods from performance-based

- engineering [29] a useful *IM* for performance-based blast assessment and design will be presented,
- together with the analytical evaluation of Eq. (1) in a format that is useful for practical applications.

# 123 **3** The impulse density as intensity measure

Two of the main parameters that determine the blast load on structures are: the scaled distance (Z)124 and the amount of explosive or charge weight (W). Fig. 1a shows their effect on blast pressure (p) 125 and blast impulse (i) both taken as load parameters for the case of surface burst explosions [2]. The 126 127 stand-off distance R is measured from the target to the explosive source, while the scaled distance Zis obtained by dividing R by the cube root of the explosive charge weight W.  $p_0$  is the side-on 128 129 pressure,  $p_r$  is the reflected pressure,  $i_0$  and  $i_r$  are the side-on and reflected impulse densities, respectively [2]. Based on the UFC 3-340-02 [2] manual the blast load can be defined as an 130 131 equivalent triangular pulse as indicated in Fig. 1a, where  $t_d$  is the equivalent triangular pulse 132 duration. Via the functional relationships shown in Fig. 1a in terms of the scaled distance and explosive weight, a direct dependence of the blast load on both peak pressure  $p_{peak}$  ( $p_r$  in the case of 133 Fig. 1a) and impulse density (i) can be observed. 134



Fig. 1: (a) Blast load parameters [2]; (b) design blast load shapes [2]

Fig. 2a represents an iso-response curve, i.e., a curve of constant structural demand D (in this case referring to the support rotation  $\theta$ ), plotted as a function of both the peak pressure and the impulse density of the blast load. The chart shown in Fig. 2a is called pressure-impulse diagram and it is very common in blast engineering when designing structural elements [30]. The pressure-impulse diagram indicates that the structural response depends on both peak pressure p and impulse density *i*. Therefore a comprehensive *IM* to adopt in blast design should be the vector (p,i) and consequently

- 141 the fragility is best represented by a surface P(D|p,i) instead of a curve P(D|i) or P(D|p). As
- 142 previously stated, identifying cases where the vector can be reduced to a scalar parameter is
- advantageous, as it would reduce the computational effort by an order of magnitude.

144 The relationship between *i* and *p* is well known in current design procedures that are based on a single pressure-impulse diagram for a component [31 - 37]. Fig. 2a shows the different regions of 145 146 the pressure-impulse diagram: i) the impulsive region  $(I_R)$  where only the impulse density is 147 relevant for the structural response of a component; ii) the dynamic region  $(D_R)$  where the structural 148 response of the component is governed by the load shape and the pressure magnitude; and finally 149 iii) the quasi-static region  $(S_R)$  where only the peak pressure is relevant for the structural response 150 of a component. If a probabilistic approach is adopted, an infinite number of such pressure-impulse 151 diagrams should be considered for the specific response level, each one corresponding to a single 152 value of the probability of exceedance between 0 and 1. Each pressure-impulse diagram is a cross 153 section of the above mentioned P(D|p,i) fragility surface, defined by a plane at constant probability 154 of exceedance  $P_0$ . Each fragility curve P(D|i), where impulse is the *IM*, is a cross-section of P(D|p,i)155 defined by a plane at a constant pressure. Fig. 2a shows these cross-sections of the fragility surface 156 that define the fragility curves, each one for a constant value of the pressure. This direct relationship 157 between the constant-pressure fragility curves (Fig. 2a) and the pressure-impulse diagram (Fig. 2a) is crucial because from the fragility curves of Fig. 2a the pressure-impulse diagram for a constant 158 159 conditional probability of exceedance can be immediately obtained, e.g., as in Fig. 2a. Then, the 160 points of a certain pressure-impulse diagram can be viewed as a series of iso-probability impulse 161 values, each one belonging to a different P(D|i) fragility curve, as shown in the illustrative example of Fig. 2. 162

163 The P(D|i) fragility curves of Fig. 2a are practically coincident when the pressure value belongs to 164 the impulsive region. This is because in the impulsive region a change of the pressure does not 165 imply a significant variation of the structural response and, consequently, of the structural fragility. 166 On the other hand, when the pressure value moves toward the dynamic and quasi-static regions the 167 fragility curves become substantially different.



Fig. 2: Probabilistic description of the blast response for a structural component. (a) Generic pressure-impulse diagram; (b) structural fragility conditioned on impulse for different given pressures  $p_i$  (i = 1-6). For  $p_i$  in the impulsive region, the curves are essentially coincident.

- 168 For most blast-resistant structural elements the loading conditions due to detonations of high 169 potential explosives are generally associated with the impulsive region of the pressure-impulse 170 diagram. Therefore the impulse density (i) is selected as IM to characterize the blast load. However, 171 for very stiff and heavy structures, the loading conditions can be on the dynamic or quasi-static 172 region of the pressure-impulse diagram; for this kind of structures the impulse density is an insufficient IM and can lead to over estimation of the probability of exceedance (i.e., bias). 173 In Fig. 3a a general pressure-impulse diagram is shown. The choice of *i* as intensity measure means 174 175 that for a pressure value  $p_0$  belonging to the impulsive region of the pressure-impulse curve a range 176 of the impulse  $\Delta i$  can be identified, spanning within points "a" (P(D>C|i) =  $\varepsilon$ ) and "c" (P(D>C|i) = 177 1- $\varepsilon$ ) (where  $\varepsilon \ll 1$ ) in Fig. 3a. In this region, the pressure-impulse curve can be approximated only 178 by its impulsive asymptote. This trend defines a curve representing the structural fragility for 179 impulse sensitive structural elements; see Fig. 3a. In order to obtain the above fragility curve, a 180 number of load samples (pairs of the explosive charge and the stand-off distance) can be 181 considered. Each load sample is defined by both a peak pressure and an impulse density in order to characterize, e.g., the triangular load shape (in the latter case the decay coefficient should also be 182
- defined [35]). The load sample should belong to an appropriate region located in the pressure-
- impulse plane around point "b", as shown in In Fig. 3a.



Fig. 3. Conceptual definition of the fragility curve for impulse sensitive structures

# 185 4 Probabilistically-consistent safety factor approach

186 The evaluation of the integral in Eq. (1) can be simplified by a number of appropriate assumptions. 187 First, both demand *D* and capacity *C* are assumed to be lognormally distributed, having median 188 values of  $\hat{i}_c$ ,  $\hat{i}_D$  and dispersions (standard deviations of the log data) of  $\beta_C$  and  $\beta_D$ . The latter are 189 numerically almost the same as  $V_c$  and  $V_d$ , the coefficient of variations of the capacity and demand 190 respectively, at least for values less than about 0.6. Then, following the derivation of Cornell et al. 191 [29], it can be shown that for uncorrelated demand and capacity, Eq. (1) becomes:

$$P(C < D) = 1 - \Phi\left(\frac{\ln \hat{\imath}_C - \ln \hat{\imath}_D}{\sqrt{\beta_C^2 + \beta_D^2}}\right)$$
(2)

192 Where  $\Phi$  is the cumulative distribution function (CDF) of the standard normal distribution. If we let 193 *x* represent the Acceptable Probability of Exceedance (APE),  $\Phi^{-1}$  be the inverse of  $\Phi$ , and  $K_{APE}$  be 194 the standard normal variate corresponding to non-exceedance probability of 1-*x*, then checking for 195 P(C < D) < x can be transformed via Eq. (2) into Eq. (3) and Eq. (4) [29, 38].

$$\lambda = e^{K_{APE}\beta_T} < \frac{\hat{\iota}_C}{\hat{\iota}_D} \tag{3}$$

where

$$\beta_T = \sqrt{\beta_C^2 + \beta_D^2}; \quad K_{APE} = \Phi^{-1}(1-x)$$
 (4)

196

197 The safety factor ( $\lambda$ ) is defined by Eq. (3) and can be broken into familiar demand and capacity 198 factors, each ruled by the corresponding dispersion. Safety checking simply becomes a test of 199 whether the ratio of  $\hat{\iota}_c/(\lambda \hat{\iota}_D)$ , exceeds 1.0.

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The proposed safety factor is thus intended to be applied as multiplier of the median demand intensity for a probabilistically-consistent design of structural elements. Wherever a monotonic relationship is available that connects impulse density (the *IM*) with structural response, this relationship can be used to connect the median response to the median intensity. Then, Eq. (3) can be used to incorporate the effect of uncertainty into design decisions. For example an approximate formula for predicting the maximum deflection  $y_{max}$  of a component in case of impulse sensitive structures is as follows [30]:

$$y_{max}(i) = \frac{1}{2} \left( \frac{(iA)^2}{(K_{LM} M) S_y} + d_y \right)$$
(5)

207 In Eq. (5) A is the loaded area of the element, *i* is the impulse density of the demand, M is the total mass of the element,  $S_v$  and  $d_v$  are the yield resistance and displacement respectively of the element, 208 209 and  $K_{LM}$  is the load-mass transformation factor (see following sections). The component must be assured to maintain  $y_{max}$  lower than the threshold value  $y_{LS}$  of the considered limit state. This can be 210 211 simply done by comparing  $y_{LS}$  against the value of  $y_{max}(\lambda i)$ , where  $\lambda$  has been derived for the desired 212 APE and the appropriate dispersions of demand and capacity. Note that a lognormal PDF is not 213 necessarily preserved in the transformation of variables from structural response to intensity, thus 214 Eq. (3) only becomes a rough but still useful approximation.

#### 215 5

# 5 Hazard analysis of the case-study

216 To showcase the proposed approach, we shall consider a case-study of a blast-resistant door subject 217 to accidental explosions of ammunitions. The steel built-up blast resistant door under consideration 218 is located in the exterior side of a building belonging to a military facility. Along the side of the 219 building there is a street transited by military vehicles carrying boxes of 60 mm mortar rounds in 220 various quantities. Each metal ammunition box contains four High Explosive (HE) 60 mm mortar 221 rounds, each containing 160 g (0.34 lb) of TNT [30]. The vehicles (jeep or van) generally carry about twelve ammunition boxes leading to a median explosive weight of 7.7 kg of TNT. At 25% 222 223 and 75% of the cases, no more than ten and fifteen ammunition boxes are carried, respectively. 224 Consequently a lognormal distribution with the coefficient of variation of 0.31 fits well with the 225 total amount of explosive on an arbitrary military vehicle. Furthermore, the properties of the 226 lognormal probability density function allow us to take into account rare cases where the vehicle is 227 loaded over the "maximum considered" number of ammunition boxes.

- As there are multiple identical blast doors along the length of the building, detonation is assumed to
- 229 occur right opposite one of them, with the vehicle occupying any spot along the road cross-section
- with the same probability. With reference to Fig. 4,  $R_1$  is the distance between the door and the edge
- of the road,  $R_2$  is  $R_1$  plus the sidewalk length, and finally  $R_3$  is the distance from the detonation
- point to the sidewalk.  $R_2$  is equal to 2m, while the stochastic variable  $R_3$  is characterized by a
- uniform (non-informative) PDF between 0 and 7m. The stand-off distance is the sum of  $R_2$  and  $R_3$ .



Fig. 4: Description of the blast scenario and of the considered variables; distances in [cm]

The lognormal PDF of the impulse density, shown in Fig. 5, is obtained by extracting 10<sup>5</sup> samples of both the explosive charge and the stand-off distance from their respective PDFs. The equivalent triangular pulse is computed as shown in Fig. 1a. All the terms in Fig. 1a are computed by the procedure proposed in the UFC 3-340-02 [2] manual. The resulting median value and dispersion of the impulse density demand are equal to 0.614 kPa sec and 0.601, respectively.

239



Fig. 5: Lognormal probability density function of the impulse density

# 240 6 Limit state definition for fragility analysis of the case-study

241 UFC 3-340-02 [2] provides the state of practice for designing structural elements against accidental

explosions. A specific section of the UFC 3-340-02 [2] manual is focused on special considerations Page 10 of 32

- about blast resistant doors, where basic procedures and performance requirements are defined. More
- 244 detailed design procedures for such elements are included in the Unified Facilities Guide
- 245 Specifications (UFGS) 08-39-54 [39]. Blast resistant doors are conceived to contain an explosion
- and therefore prevent the propagation of pressure, fireball leakage and fragments inside the
- **247** protected area [40 43].
- 248 There are different typologies of blast doors, classified on the basis of their structure (e.g. single
- leaf or double leaf) and on the basis of the opening mode (e.g. vertical lift and horizontal sliding).
- There are also several kinds of standard performance requirements for categorizing the blast doorsaccording to their function. Performance requirements include:
- 252 protection of personnel and equipment from external blast pressures resulting from an
   accidental explosion;
- 254 prevention of accidental explosion propagation into an explosive storage area;
- 255 maintain complete serviceability for doors designed as part of a containment cells
   256 commonly used in the repeated testing of explosives;
- 257 maintain integrity for doors designed as part of containment structures commonly used to
   258 protect nearby personnel and structures in the event of an accidental explosion.
- For our case-study a  $L_x = 2500$  mm high and  $L_y = 1400$  mm wide built-up steel door with a single leaf is considered. The door is made by welding steel plates to a steel beam grid. The grid is made up of UPN 80 beams on the boundaries that support four L 80x60/7 spandrel beams. On top of them, the exterior plate is 5 mm thick and the interior plate is 1 mm thick (see Fig. 6).





Fig. 6: Details of the case-study blast resistant door. Frontal view (a); section along the width (b); section along the height (c). Dimensions in [mm].

Adopting a performance-based philosophy four limit states are considered related to Serviceability,

264 Operability, Life Safety and Critical Failure of the blast resistant door (Table 1). For this purpose

265 one or more response parameters and appropriate threshold values of these parameters need to be

266 defined. The selected response parameters are: the support rotation ( $\theta$ ) and the ductility ratio (*m*):

$$\theta = \arctan\left(\frac{2y_{max}}{L_y}\right) \tag{a}$$

$$m = \frac{y_{max}}{d_y} \tag{b}$$

Where  $y_{max}$  is the maximum displacement of the component,  $d_y$  is the yield displacement (measured at the same position as the maximum), and  $L=L_y$  is the span of the component. In this case  $L_y$  is considered because, being shorter than  $L_x$ , it leads to a larger support rotation; more details are provided in the following sections.

A general consensus concerning the threshold values for the different limit states has not been 271 272 reached in the scientific community. The adopted values have been chosen by means of a critical 273 examination of both the literature and the physics of the problem, also with the support of 274 appropriate numerical analyses described below. Note that different threshold values of a response 275 parameter are expected for different typologies of the blast resisting doors. In order to give an idea of the uncertainty affecting the threshold values, a Qualitative Confidence Index (QCI) [44] is 276 277 provided in the table, ranging from "high" (low level of uncertainty) to "low" (high amount of 278 uncertainty).

The first limit state is Serviceability, the blast door should be fully operable after the event without need for repair. Damage to both the door structure and door accessories (like the panic opening system) is not allowed. The ductility ratio m is the response parameter chosen for this LS, with a threshold value (indicating violation) equal to 1.0. For Operability the door should be able to be opened. Damage to the door structure is allowed, but damage to the door accessories is not. Thus,

the door should remain operable after the event, even if permanent deformations are present. This is 284 important for avoiding failure and/or blockage of the panic opening system of the door in a way that 285 both the evacuation of the building and the police/firemen operations can be easily conducted. In 286 287 the case of Operability the support rotation is selected as the response parameter with a threshold 288 value of 2 degrees [2, 42]. For Life Safety the inoperability of the door after the event is acceptable 289 but the structure must not fail; significant permanent deflections of the door are still allowed; to 290 satisfy the Life Safety criteria the support rotation is limited to a threshold value of 10 degrees. This value is chosen on the basis of the results obtained by a static pushover analysis of the case-study 291 292 built-up door (see next sections). The last limit state is the Critical Failure and it occurs when the 293 structural response of the door is causing the projection of the door itself or parts of it into the 294 protected space.

Finally, as qualitatively assessed by the QCI, the dispersion on the thresholds defining the limit states can be taken into account by considering the threshold values as stochastic variables. By using Eq. (3) to estimate the safety factor, the dispersion of each limit state can be taken into account as shown in Eq. (7) where  $\beta_{LS}$  is the additional epistemic uncertainty dispersion of the limit state threshold.

$$\beta_T = \sqrt{\beta_C^2 + \beta_D^2 + \beta_{LS}^2} \tag{7}$$

Further investigations should be undertaken in order to assign a probability density function to the
threshold values of the limit states in case of steel built-up blast resistant doors. Threshold values of
the limit states are assumed here as deterministic parameters.

Limit State	Serviceability	Operability	Life Safety	<b>Critical Failure</b>
Damage level	The door has no permanent deflections	The door is operable, but it has permanent deflections	The door has not failed, but it has significant permanent deflections	The door has failed
Response	Ductility ratio	Support rotation	Support rotation	Support rotation
parameter	(m)	$(\theta)$	$(\theta)$	$(\theta)$
Threshold values	<1	<2°	<10°	>10°
QCI	High	Medium	Low	Low

303

304 Table 1: Considered limit states and threshold values

#### **305 7 The Simplified Stochastic Model (SSM)**

As early mentioned, a Simplified Stochastic Model (SSM) has been used to evaluate the fragility of
the blast door. The SSM is an equivalent Single Degree of Freedom (SDOF) model of the steel
built-up door, taking into account both the aleatory and epistemic uncertainties.

309 The equivalent SDOF system is obtained by evaluating appropriate transformation factors for the system's mass, damping, load and resistance. Furthermore, inherent within a SDOF analysis is the 310 311 assumption that the system behaves only in a single deflection shape. In general, as the system 312 begins to deflect under the blast load, it eventually yields and forms plastic hinges at various locations depending on the applied boundary conditions. Thus in reality, the system's mode shape 313 314 changes with the progression of plastic hinges. Therefore, the transformation factors are adjusted to 315 take into account the change of the mode shape. For a simply supported one way panel under 316 uniform loading, it is assumed that a single plastic hinge is formed at the center of the element. The 317 resistance-deflection relationship for such a panel is assumed to have an elastic-perfectly plastic 318 shape. Thus, at a certain yield deflection, the component will continuously deform at near-constant 319 resistance until an ultimate deflection limit is reached; at that point the component will fail. This 320 resistance-deflection relationship (resistance function) serves as constitutive relation for the non-321 linear stiffness in the equation of motion.

The displacement field of the component can be expressed as  $u(x,t)=\psi(x)y(t)$ , where  $\psi(x)$  is the assumed deformed shape of the component under the blast load and y(t) is the displacement of the component at the location of maximum deflection at time *t*. Furthermore, displacement of the component is obtained by the SDOF equation:

$$K_{LM}M\ddot{y}(t) + C\dot{y}(t) + S(y(t)) = F(t)$$
(8)

326 where M is the total mass of the component, S(y(t)) is the resistance as a function of the 327 displacement expressed in unit force, F(t) is the blast pressure multiplied by the loaded area A 328 expressed in force units, C is the damping (the percentage of the critical damping is assumed to be 329 1% in the analyses),  $K_{LM}$  is the load-mass transformation factor, that is equal to the ratio of  $K_M$  and 330  $K_L$  (the mass transformation factor and the load transformation factor respectively). The last two are evaluated by equating the energy of the two systems (in terms of work energy and kinetic energy 331 332 respectively). The load-mass transformation factor  $K_{LM}$  is different at each deformation stage of the 333 component response; for a bilinear resistance function two values of  $K_{LM}$  need to be defined: the 334 first for the elastic and the second for the plastic range of the response [2, 45].

- 335 The built-up blast door considered is a two-dimensional orthotropic structure and it is made
- equivalent to a SDOF model with a bilinear resistance function. For obtaining such a resistance
- function, the yield point  $(P_y)$  needs to be defined, characterized by the yield blast pressure  $(r_y)$  and
- the corresponding yield displacement  $(d_y)$  of the door. In order to define the  $r_y$  and the  $d_y$  both
- aleatory and epistemic uncertainties are introduced.
- 340 In Eq. (6) the formulas for computing  $r_y$  and  $d_y$  are shown.

$$r_{y} = \left(\frac{12}{L_{x} L_{y}}\right) \left(M_{px} + X_{A} M_{py}\right) \quad (a)$$
$$K_{e} = X_{B} \frac{E\left(\frac{J_{y}}{L_{x}}\right)}{L_{x} L_{y}^{3}} \qquad (b) \quad (9)$$

$$d_y = \frac{I_y}{K_e} \tag{c}$$

- where,  $K_e$  is the stiffness of the SDOF,  $L_x$  and  $L_y$  are the longer and shorter dimensions of the door respectively, and *E* is the Young's modulus of steel. The coefficients  $X_A$  and  $X_B$  are taken equal to 1.374 and 198.6 respectively, and they are valid for orthotropic plates with  $L_y/L_x$  equal to 1.78 [2, 45, 46].  $J_x$  and  $J_y$  are the moments of inertia, while  $M_{px}$  and  $M_{py}$  are the flexural plastic moments of the two orthogonal cross sections of the built-up door.
- 346  $L_x$ ,  $L_y$ , and E are assumed to be deterministic parameters, i.e., well known for a steel door; instead 347 both  $J_y$  and  $J_x$ , and consequently  $M_{px}$  and  $M_{py}$  are considered as stochastic parameters in order to 348 take into account the epistemic uncertainties. Moreover, the aleatory uncertainty affecting the yield 349 stress of steel is considered.
- 350 With reference to Fig. 6 the door moments of inertia are computed by Eq. (10)

$$J_{x0} = 2J_{UPN} + (L_y t_1^3)/12 + (L_y t_2^3)/12$$
(a)

$$J_{y0} = N_L J_L + 2 J_{UPN} + \left[ (L_x t_1) \left( (H_L + 0.5 t_1) - d_G \right)^2 \right] + \left[ (L_y t_2) (0.5 t_2 + d_G)^2 \right]$$
(10)  
+  $(L_y t_1^3)/12 + (L_y t_2^3)/12$ (b)

where,  $N_L$  is the number of spandrels orthogonal to  $L_x$ ,  $J_L$  and  $J_{UPN}$  are the moments of inertia of the spandrels and of the external frame respectively,  $t_1$  and  $t_2$  are the thicknesses of the plates on the blast side plate and the opposite side respectively, and  $d_G$  is the center of mass of the composite

- section. For computing  $J_{x0}$  the additional moment of inertia due to the plates is not considered
- because there are no spandrels connecting the plates along the  $L_x$  direction.
- 356 Noting that in the following the subscript "*i*" is adopted in order to indicate the single sample of the
- 357 Monte Carlo simulation and the stochastic coefficient  $\alpha$  is introduced to take into account the
- uncertainty of the moments of inertia. The sample values  $J_{xi}$  and  $J_{yi}$  are evaluated as shown in Eq. (11).

$$J_{xi} = \alpha_i J_{x0} \quad (a)$$
(11)  
$$J_{yi} = \alpha_i J_{y0} \quad (b)$$

360

361  $M_{pxi}$  and  $M_{pyi}$  are computed by Eq. (12) considering also Eq. (13).

$$M_{pxi} = \sigma_{ydi} \varphi_i \alpha_i \frac{J_{xi}}{b_x} \quad (a)$$

$$M_{pyi} = \sigma_{ydi} \varphi_i \alpha_i \frac{J_{yi}}{b_y} \quad (b)$$
(12)

362

$$\sigma_{ydi} = \sigma_{yi} DIF_i \quad (a)$$

$$DIF_i = 1 + DIF_{0i} \quad (b) \quad (13)$$

$$\varphi_i = 1 + \varphi_{0i} \quad (c)$$

363

In the above equations  $b_x$  and  $b_y$  are the longest distances between the center of mass and each of the two external sides of the cross sections, while  $\sigma_{ydi}$  and  $\sigma_{yi}$  are the sample values of the dynamic and static yield stress of steel, respectively, assumed to be random. The sample value *DIF<sub>i</sub>* of the Dynamic Increase Factor, is obtained as one plus the decimal part *DIF<sub>0i</sub>*, the latter assumed to be random to consider epistemic uncertainty. Finally  $\phi_i$  is the sample value of the plastic coefficient obtained as one plus the decimal part  $\phi_{0i}$ ;  $\phi_{0i}$  is assumed as a stochastic variable affected by uncertainty.

- 371 The considered stochastic variables are summarized in Table 2 together with their distribution
- 372 characteristics. The mean value of  $\alpha$  is set equal to unity; the mean value of  $\sigma_y$  is estimated by
- assuming a strength factor equal to 1.1 [45], leading to a mean value of  $\sigma_y$  equal to 302.5 MPa for a
- 374 steel having tensile strength equal to 450 MPa; the mean value of  $\phi$  is estimated by fitting the

375 resistance of the SSM with the static pushover curve computed by the FE model as described in what follows; finally the mean value of the DIF is provided in the Methodology Manual for the 376 SDOF Blast Effects Design Spreadsheets [45] for an equivalent grade of steel. With regard to the 377 dispersion of these coefficients, the coefficient of variation of  $\sigma_v$  is taken from the study of Enright 378 379 and Frangopol [47]; while the coefficient of variation of both  $\alpha$  and  $\phi$  are estimated by means of the dispersion of  $P_{y}$  with respect to the static pushover curve obtained by the FE model. The coefficient 380 381 of variation of the DIF is estimated by the values of the DIF provided by the Methodology Manual 382 for the SDOF Blast Effects Design Spreadsheets [45] for several strain rate velocities. 383

Parameter	Median value	COV	Distribution
$\sigma_y$	302.5 MPa	0.12	lognormal
α	1	0.1	lognormal
$\phi_{o}$	0.3	0.1	lognormal
$DIF_0$	0.19	0.2	lognormal

384

385 Table 2: Probabilistic distributions of the stochastic variables

386

By substituting the sample values obtained in Eq. (11), (12) and (13) into the Eq. (9), the sample  $P_{yi}$ of the yield point  $P_y$  of the resistance function is computed. The resulting median value of  $r_u$  and  $d_y$ are 306 kPa and 6.8 mm respectively, while their coefficient of variation are 0.16 and 0.125 respectively.

# **8 Validation of the SSM by the Finite Element model**

In order to validate the SSM a detailed Finite Element Model (FE model) is developed, using the 392 commercial FE solver LS-Dyna<sup>®</sup> [48] and employing shell elements for the constituent parts of the 393 394 blast door. The support frame of the door is also explicitly modeled in order to accurately take into 395 account the unilateral boundary conditions by making use of contact elements. Additional contact 396 elements are provided for the door opening hinges and door locking system for allowing the 397 rebound response. In total the model consists of 84794 shell elements and 85062 nodes. The shell 398 elements are of Belytschko-Tsay type [48] and the contact algorithm is the automatic surface to 399 surface [48].

With regard to steel, a piecewise linear plasticity model [48] is adopted, see Fig. 7. The engineering
stress-strain curve is taken from the study of Kalochairetis et al. [49] by a quasi-static experimental
test considering the length and the initial cross sectional area of the specimen; instead the true

403 stress-strain curve is obtained analytically by assuming logarithmic strains [48]. Furthermore, a 404 fracture criterion is implemented without taking into account the effect of the stress triaxiality; the 405 fracture occurs when the effective plastic strain reaches the value 0.2473 corresponding to the 406 maximum resisting stress before softening. The strain rate effect is taken into account by a *DIF* 407 computed by the Cowper and Symonds model shows in Eq. 14 [48], where  $\xi$  is equal to 500 [1/s] 408 and  $\gamma$  is equal to 6 [45].

$$DIF = 1 + \left(\frac{\dot{\varepsilon}}{\xi}\right)^{\frac{1}{\gamma}} \quad (14)$$

409 It is crucial to highlight that the steel yield stress shown in Fig. 7 does not match the mean value of 410 the steel yield stress of Table 2. In order to validate the SSM by the FE model, the input parameters 411 are assumed to have the mean values and the steel stress-strain relationship shown in Fig. 7.

412 Furthermore a *DIF* equal to 1 and 1.19 for the case of the static and dynamic response respectively

413 has been assumed for the SSM.

414



415

In Fig. 8a the FE model and details of the built-up door are shown. A magnified view of the FE
model is presented in Fig. 8a. The characteristic dimension of the single rectangular finite element
is 15 mm and it is quite constant for the entire mesh. As needed, a sensitivity analysis has been
conducted regarding the mesh refinement, whose results are not reported here for the sake of
brevity.





# 421 8.1 Deterministic static resistance function

422 In order to obtain the static resistance function of the built-up blast door a static pushover analysis is carried out by applying a uniform load to the blast side plate. The uniform pressure is applied quasi-423 424 statically by a ramp load function until the collapse of the door is reached. In Fig. 9 the static resistance functions computed by the SSM (by assuming the mean values of the input parameters) 425 and the FE model are shown. In Fig. 9a the static resistance function is plotted as a function of the 426 427 mid-span displacement y, while in Fig. 9a it is plotted as a function of the support rotation  $\theta$  defined 428 in Eq. 6. Especially for the range of support rotation from 0 to 2 degrees there is a good agreement 429 between the two predictions, while introducing a positive stiffness post-yield stress-strain model 430 would easily extend this to rotations of 6 degrees or more. However, only appropriate experimental 431 tests could fully confirm the results.



Fig. 9: Static resistance function of the case-study door (the adopted steel is the one having the stress-strain relationship shown in Fig. 7).

432

# 433 8.2 Deterministic dynamic structural response

The FE model and the SSM are then compared in terms of dynamic structural response. The built-up door is subjected to four detonations and the structural response is computed by both the SSM

and the FE model. All the detonations occur at 500 mm from the ground and at 6 m away from the
door. The explosive charges of the four detonations are assumed to consist of 10, 15, 20, 25 kg of
TNT. The blast pressure is assumed as uniformly distributed in the SSM, but it is properly
evaluated as non-uniformly distributed in the FE model by the LS-Dyna<sup>®</sup> function named load blast
[48]. Only the positive phase of the shock wave is taken into account by the equivalent triangular
pulse, alternatively an exponential decay law can be adopted [35].

442 Concerning the parameters characterizing the SSM, the values adopted for comparison purposes 443 with the FE model are:  $\sigma_y$ =340 MPa,  $\phi$ =1.3,  $\alpha$ =1, and *DIF*=1.19; thus it is important to recall that, as 444 mentioned above, for the successive computations of the fragility curves and of the safety factor, 445 the mean value of  $\sigma_y$  is assumed to be 302.5 MPa. In Fig. 10 the comparison between the time 446 histories of the support rotation  $\theta$  obtained with the FE model and the SSM are reported for all the 447 four detonations.



Fig. 10: Comparison between the time histories of the support rotation  $\theta$  obtained with the FE model and the SSM (SDOF in legend). 10 kg of TNT (a); 15 kg of TNT (b); 20 kg of TNT (c); 25 kg of TNT (d).

448

In Fig. 11, where the boundary conditions and plate opposite to the blast side are removed from theview for allowing the checking of the spandrels, the plastic strains on the door obtained by the FE

- 451 model are plotted. Plastic strains are represented in black color while in grey is the elastic steel (in452 the black zones the dynamic yield stress of the steel was reached).
- With reference to Fig. 10 it can be appreciated that generally there is a good agreement between the predictions of the support rotations obtained by the SSM and the FE model. However the SSM seems to be slightly conservative with respect to the FE model. Furthermore due to the non-linear boundary conditions implemented in the FE model, the rebound response and the time of the max support rotation are somewhat different, but this is not relevant for the purpose of the SSM that is to
- 458 estimate only the maximum support rotation of the built-up door.
- 459 It is noteworthy that the SDOF can well predict the deflection but no local damage. However, the
- 460 SDOF is able to predict the global behavior of the door and its failure due to excessive mid-span
- displacement or support rotation, something that is sufficient for the purposes of this paper, with
- 462 enormous reduction of the computational effort with respect to the FE analysis.

463



(a)



(b)



Fig. 11: Plastic strains on the door obtained by the FE model. 10 kg of TNT (a); 15 kg of TNT (b); 20 kg of TNT (c); 25 kg of TNT (d).

464 On the basis of the plastic strain results shown in Fig. 11, it can be stated that the non-uniform 465 distribution of the blast load does not lead to a particularly non-uniform structural response of the built-up door: the plastic strains on the spandrels are quite uniform. Furthermore, it can be argued 466 467 that the door develops a flexural resistant mechanism since only limited plasticity is developed at the connection of the spandrels with the external frame. In the case of 25 kg of TNT, Fig. 11(d), the 468 469 blast side plate shows spread of plasticity but it maintains the ability to transfer the load on the 470 spandrels; note that the previously mentioned fracture criterion is implemented in the FE model and 471 an eventual fracture of the blast side plate would be detected.

# 472 **9** Computing the fragility curves

In this section the fragility curves for the built-up blast door are developed for each limit state
previously defined. The fragility curve is computed point by point using a Monte Carlo- based
algorithm [24] and the resulting points are fit by a lognormal CDF in order to obtain a smooth curve
to use in computing the probability of exceeding the limit state and the corresponding safety factor.
The flowchart representing the steps in computing the fragility curves is shown in Fig. 12. Looking
at the flowchart, *N* is the number of the points in which the fragility curve is numerically evaluated, *j* is the loop counter identifying the Monte Carlo simulation which is performed to evaluate the

480 single point FC(*j*) of the fragility curve, corresponding to the *j*-th value  $IM_j$  of the intensity measure 481 (impulse density). For *j*=1 a Monte Carlo simulation is carried out and the conditional probability of 482 exceedance is estimated. The next step is to compute the successive point of the fragility curve, then 483 for the new value of the *IM* a new Monte Carlo simulation is performed and the conditional 484 probability of exceedance is estimated. This cycle is repeated until *j*=*N*.



Fig. 12: Flowchart of the procedure for the evaluation of the fragility curves. FC= fragility curve.

485

The first fragility curve obtained by the algorithm shown in the flowchart of Fig. 12 is called "numerical fragility curve". The final step consists of fitting the points of the numerical fragility curve in order to obtain the analytic lognormal fragility curve defined by the mean value and the standard deviation of the corresponding normal. In Fig. 13 the fragilities curves obtained for the Serviceability, Operability, and Life Safety limit states are shown. Their median values ( $\mu_{ln}$ ) and coefficient of variations ( $\beta_{ln}$ ) are shown in Table 3.



Fig. 13: Fragility curves obtained by the SSM. Serviceability (a), Operability (b), and Life Safety (c)

492

]	Limit State	Serviceability	Operability	Life Safety	Critical Failure
Resp	onse Parameter	$y < d_y$	$\theta < 2^{\circ}$	$\theta < 10^{\circ}$	$\theta > 10^{\circ}$
EC	$\mu_{ln}$ [kPa sec]	0.3080	0.8700	1.9800	1.9800
гC	$\beta_{ln}$	0.1518	0.0748	0.0785	0.0785

493

494 Table 3: Characterization of the fragility curves for the examinated limit states.

495

The number of samples ( $N_j$ ) used in the Monte Carlo simulation to compute the single point FC(j) of the numerical fragility curve is not constant;  $N_j$  is chosen for each j in order to maintain the coefficient of variation ( $COV_j$ ) of the estimated value (representative of the error due to sampling) under a maximum acceptable threshold. The  $COV_j$  is quantified as:

$$COV_{j_{P[D>C|i_{j}]}} = \sqrt{\frac{1 - P[D>C|i_{j}]}{P[D>C|i_{j}] N_{j}}} \quad (15)$$

With regard to the fragility curve associated with the Operability limit state, the variation of both the number of samples and coefficient of variation with the conditional exceedance probability P[D > C|i] is shown in Fig. 14. The number of samples decreases exponentially from the lowest to the highest probability of the numerical fragility curve. Regardless of the *COV*, though, a practical maximum and minimum number of samples of  $10^5$  and  $10^3$  respectively, is adopted. As shown in Fig. 14 the maximum coefficient of variation is less than 0.1 for a conditional exceeding probability of 0.001 and it decreases quickly; for example it is less than 0.02 for a P[D > C|i] of 0.1.



Fig. 14: Variation of both  $N_j$  and COV with P[D>C|i] for the Operability limit state

#### 507 **10 Performance assessment**

Following the conditional approach, Eq. (1) can be evaluated numerically by making use of the fragility curve P[D>C|i] and of the probability density function of the impulse density f(i) shown in Fig. 5:

$$P[D > C] = \int_{-\infty}^{+\infty} P[D > C \mid i] f(i) \ \partial i \cong \sum_{j=0}^{N} P[D > C \mid i]_{j} f(i)_{j} \Delta i_{j} \quad (16)$$

511

512 Table 4 provides the probabilities of exceedance computed by both the conditional and

513 unconditional approaches.

 $\widehat{W}$  = 7.7 kg *COV*=0.3 lognormal distribution  $R_2 = 2 \text{ m } 0 \le R_3 \le 7$  uniform distribution

Limit State	Conditional Approach (CA)	Unconditional Approach (UA)	Δ=CA-UA	Closed-form Solution (Eq. 2)
Serviceability	0.8303	0.6343	0.1960	0.8553
Operability	0.1830	0.2065	-0.0230	0.2490
Life Safety	0.0195	0.0078	0.0117	0.0179

514

Table 4: Probabilities of exceedance obtained with the conditional and unconditional approachesversus the simplified closed-form solution.

517

518 For the Operability and the Life Safety limit states both the conditional and the unconditional

approach provide quite the same probability of exceedance, the slight difference between the two

520 approaches is probably due to the differences in the coefficient of variations of the computed

521 probabilities of exceedance (Fig. 14). On the other hand, for the Serviceability limit state the

difference between the two estimations is greater than in the previous cases and the probability ofexceedance computed by the conditional approach is higher. This is because the hypothesis of

- 524 impulsive loading is not respected as can be argued from Fig. 15 and detailed below. For all
- 525 practical purposes, as long as the structure is impulsively loaded, the two methods can be
- 526 considered to be almost the same.

By adopting the mean values of the above mentioned stochastic parameters (see Table 2 and Eq.
13), the pressure-impulse curves corresponding to each limit states (average pressure-impulse
curves) are obtained by the SSM and shown in Fig. 15. Therein the *IM* samples used in the
evaluation of the probabilities of exceedance are plotted, showing that the *IM* samples fall in the
impulsive region for the Operability and Life Safety limit states, while they fall close at least to the
dynamic region for the Serviceability limit state.

533



Fig. 15: Load samples and their relative position with respect to the average pressure-impulse curves related to the considered limit states

534 Finally, in Fig. 16 the safety factor obtained for the case-study blast resistant door via Eq. (3) is

535 plotted as function of the acceptable probability of exceedance (APE) for the Serviceability,

536 Operability, and Life Safety limit states.

537



Fig. 16: Safety factor as function of the acceptable probability of exceedance. The  $\theta=2^{\circ}$  and  $\theta=10^{\circ}$  curves are practically coincident.

538 From Eq. 3a the dispersion measure  $\beta_T$  depends on the dispersion of both the capacity and the 539 demand. In the case study, looking also at Table 3, the dispersion of the capacities obtained from 540 the fragilities related to the Operability and Life Safety limit states are practically the same; this 541 leads to a nearly identical safety factor as a function of the acceptable probability of exceedance for 542 these two limit states, as shown in Fig. 16. Concerning the Serviceability limit state, the coefficient 543 of variation of the capacity is greater than the ones of the Operability and Life Safety limit state (see 544 Table 3), but it still remains quite small with respect to the dispersion of the demand (which is equal 545 to 0.601 as said in section 5). In other words, the dispersion due to the structural model uncertainty 546 is vastly inferior to the dispersion of the hazard (something that has also been observed for other 547 hazards as well, e.g. earthquakes) and the latter obviously dominates. 548 For illustrative purposes, the dispersion on the threshold value of the Operability limit state is added 549 in computing the total dispersion shown in Eq. (4) as shown in Eq. (7), thus the updated safety 550 factor is compared with the one shown in Fig. 16 for an APE of 0.2. The probability density 551 function of the limit state threshold value is assumed as lognormal with a dispersion of 0.4, 552 therefore Eq. (7) provides a total dispersion equal to 0.68, and consequently the safety factor  $\lambda(0.2)$ 553 is equal to 1.77. Considering that the original  $\lambda(0.2)$  is equal to 1.6, it is evident that adding the 554 dispersion to the threshold value of the limit state increases the value of the safety factor. As long as this additional variability is inferior to the impulse hazard dispersion (0.4 versus 0.6), the square-555 556 root-sum-of-squares combination rule in Eq. (8) means that the hazard still dominates and the safety 557 factor remains relatively similar. Otherwise, it should be expected to increase substantially. 558 Finally, a practical example is presented on using the proposed safety factor to perform a simple 559 assessment of the steel blast resistant door. Let us consider the Operability limit state ( $\theta$ =2°). The 560 median resistance function is defined by the yield point values of  $r_{\mu}$  and  $d_{\nu}$  equal to 306 kPa and 6.8 561 mm respectively, while the median value of the impulse density is 0.614 kPa sec. Both the median 562 values of the yield point and of the impulse density are computed by extracting samples as shown in 563 the previous sections. By applying Eq. (5) without regard for variability, the maximum support 564 rotation is  $1.4^{\circ}$ , thus the Operability limit state is thought to be satisfied. However, by applying Eq. 565 (5) using the safety factor  $\lambda(0.2)$  equal to 1.6 (see Fig. 16) the maximum support rotation becomes

 $3.1^{\circ}$ , meaning that the Operability limit state is not satisfied due to the effect of uncertainties.

#### 567 11 Conclusions

568 An investigation has been conducted on the use of simplifying approaches for probabilistically 569 estimating the performance of structures subject to blast hazard. First, a conditional approach has 570 been introduced using the impulse density as a sufficient intensity measure (IM) for decoupling the 571 evaluation of blast hazard and the determination of structural response for impulse-governed case 572 studies. This essentially reduces the, otherwise necessary, Monte Carlo simulation into the 573 evaluation of the *IM* hazard distribution and the fragility of the structural system, and thus decreases 574 the computational load by several orders of magnitude. Second, a safety factor approach, similar to 575 existing load-and- resistance-factored design (LRFD) formats, has been suggested to offer even 576 simple estimates of the probability of violating the limit state. Moreover, the relationship between 577 the fragility (surface and curve) and the pressure-impulse diagram of a component has been clarified. 578

579 A steel built-up blast resistant door was employed as a tested to determine the probability of 580 exceedance through the conditional, the unconditional, and the safety factor approach. As expected, 581 as long as the component demand is governed by an impulsive load, the conditional method based 582 on the impulse density can significantly reduce the computations needed to determine the system's performance. The proposed closed-form safety factor managed to offer a practical estimate of the 583 584 probability of limit-state violation at the expense of some additional error. Moreover, such analytic 585 solutions were shown to offer useful insight. For example, as known in other fields of engineering, when the dispersion of the demand is greater than the dispersion of the capacity, the overall 586 587 estimates of probability mainly depend on the hazard rather than the model uncertainty. Thus, one 588 can often forego the variability in the model without biasing the analysis. In summary, we hope that 589 the groundwork has been established for using simplified probabilistic procedures for the 590 Performance-Based Design (PBD) of structures subjected to blast.

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