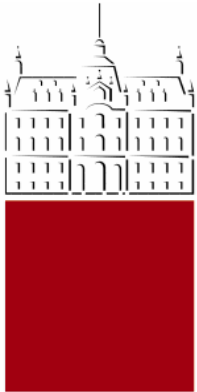


The 42nd Risk, Hazard & Uncertainty Workshop

Hydra Island, June 22-25, 2016

Design of structures for tolerable seismic risk using non-linear methods of analysis



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Introduction and motivation

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- Current building codes do not support design for a target seismic risk
- Basic research project: development of the methodology and tools for the design of structures for tolerable seismic risk using non-linear methods of analysis

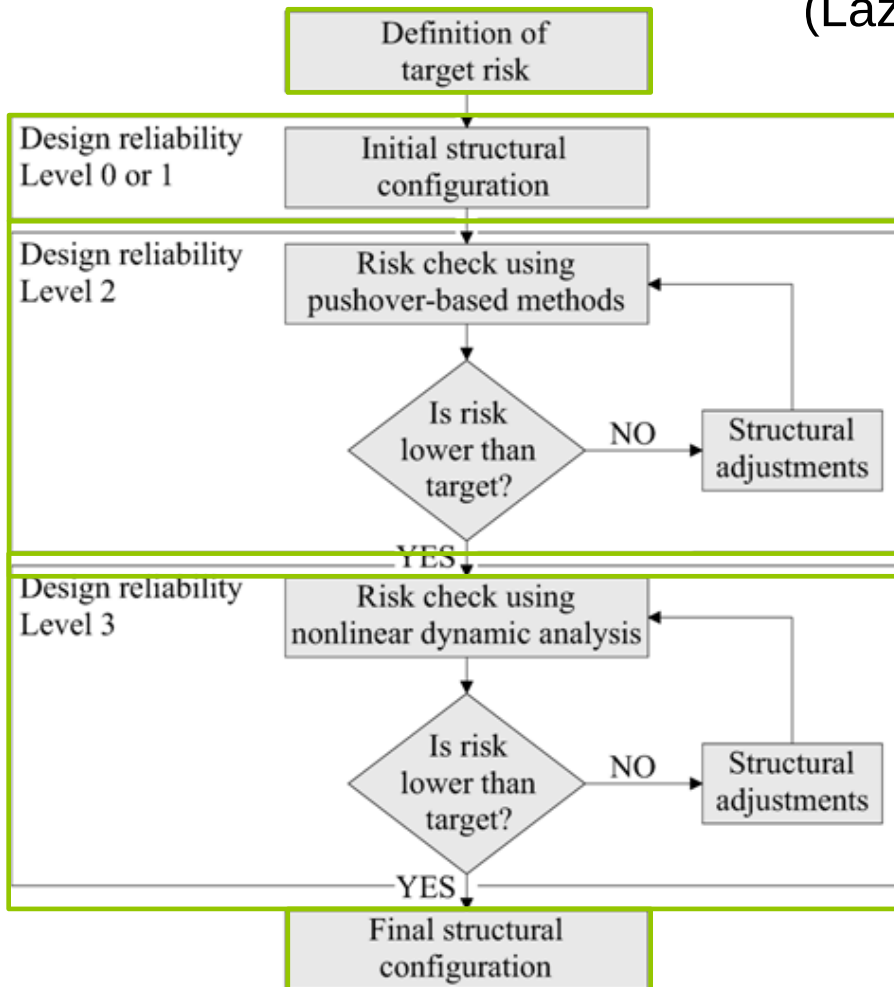


Risk-based seismic design

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One possible realization of risk-based seismic design

(Lazar Sinković, Brozović & Dolšek 2016)



- Risk-targeted force-based design (Žižmond & Dolšek, 2015)
- **SMART** Web Application for the selection of risk-targeted q-factors
- Guidelines for the structural adjustment of RC frames using pushover analysis
- 3R Method (Dolšek & Brozović, 2016)
- Risk-based decision making: NRHA for 7 GMs at a single intensity
- **SMART** CGM Web Application

Risk-based seismic design

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Adjustment of the structure using PA:

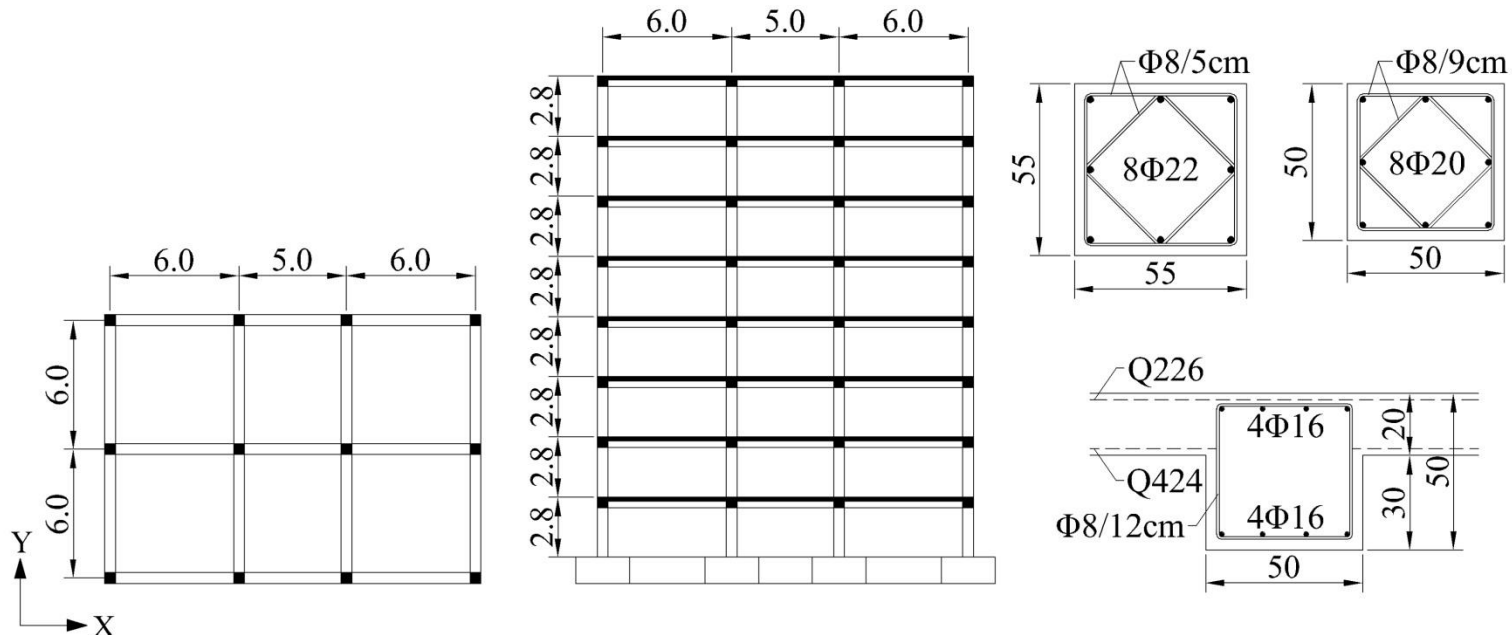
- Adjustment guidelines (Lazar Sinković, Brozović & Dolšek, 2016):
 - 0) Basic guideline: Apply the SCWB principle
 - 1) Improve deformation capacity of the system by increasing the longitudinal reinforcement in the columns (50% of maximum drift) and check if longitudinal reinforcement ratio do not exceed max value.
 - 2) Increase strength of the structure by increasing cross-section area of beams in all stories when it is required to increase the strength significantly. Check SCWB.
 - 3) Increase strength of the structure by increasing cross-section area of columns if the maximum utilization ratio is large.

Risk-based seismic design

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Example application: 8-storey RC frame

- Target collapse risk: $P_t=10^{-5}$
- Initial structure configuration: minimum requirements according to EC2 and EC8
- Material: Concrete class C30/37 and reinforcing steel S500

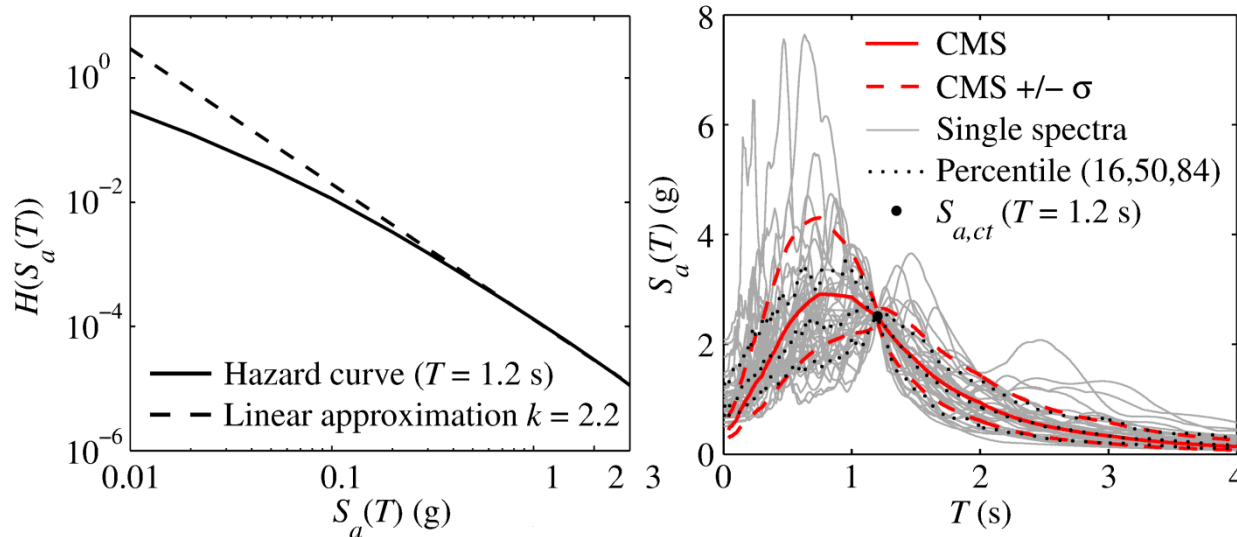


Risk-based seismic design

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Seismic hazard and ground motion selection

- Hazard: $S_a(T=1.2 \text{ s})$ for Ljubljana (Slovenia), soil type C
- Ground motion selection (according 3R method):
- 40 GMs selected according to conditional spectrum for the characteristic (16 th percentile) value of the target fragility curve: $S_{a,ct}=2.5 \text{ g}$
- Target scenario: $\varepsilon=2.0$, $M=7.3$, $R=19.2 \text{ km}$



- $P_t=10^{-5}$
- frag. LN
- $\beta=0.4$

Risk-based seismic design

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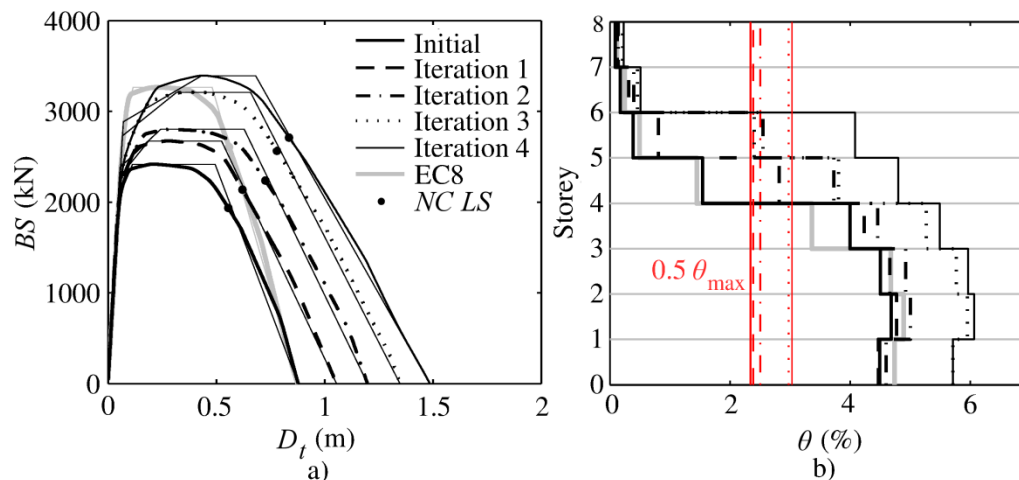
Adjustment of the structure and risk check using PA:

Iteration	Adjustment by guidelines			BS (kN)	ΔBS (%)	$D_{I,NC}$ (m)	$\Delta D_{I,NC}$ (%)	$S_{a,C,16}$ (g)	P_C ($\cdot 10^{-5}$)	ΔP_C (%)
	a) AsC	b) AcB	c) AcC							
Initial	/	/	/	2417	/	0.56	/	1.56	3.06	/
1	1-8 0.002	/	10%	2674	11	0.62	11	1.87	2.02	-34
2	1-5 0.004	/	/	2801	5	0.73	18	2.22	1.36	-33
3	1-8 0.004	5%	10%	3210	15	0.78	7	2.38	1.14	-16
4	1-6 0.004	/	/	3392	6	0.84	8	2.60	0.93	-18

AsC 1-x $\Delta\rho$: Increment of the longitudinal reinforcement ratio $\Delta\rho$ of the columns in the storeys from 1 to x

AcC ΔA_c : Increment of the cross-sectional size ΔA_c of the columns in all the storeys

AcB ΔA_c : Increment of the cross-sectional size ΔA_c of the beams in all the storeys



Risk-based seismic design

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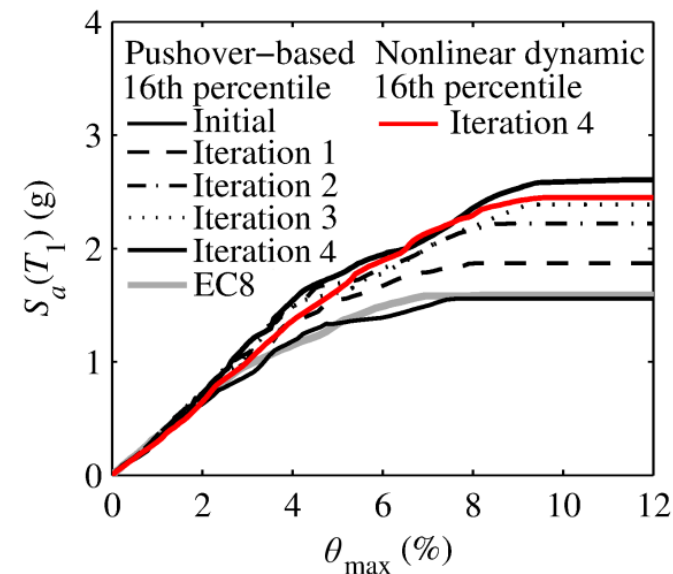
Design check – 3R method (Dolšek & Brozovič, 2016)

□ Procedure:

- 7 GMs are selected – median is close to the 16th percentile of the proxy for the collapse fragility curve (SDOF approximation)
- Dynamic analysis for 7 GMs, scaled to $S_{a,ct}$ (target value)
- 3 GMs out of 7 caused collapse: $r=3/7 < 0.5$ → The seismic risk $< P_t=10^{-5}$
(actual risk based on IDA is $P_c=0.98 \cdot 10^{-5}$)

□ Key assumptions:

- β is assumed (e.g. Kosič, Dolšek & Fajfar, 2016)
- The pushover analysis provides a good approximation of the 16th percentile collapse fragility curve



Risk-based seismic design

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Remarks and Conclusions:

▣ Advantages:

- Includes an explicit check of risk-based performance objectives in the design (increased reliability of design solutions)
- Engineer controls adjustment of structure (better insight into the behavior of the structure during earthquakes)

▣ Efficiency of the design:

- Depends on guidelines for the adjustment of structure
- Depends on engineer's knowledge and experience

Software development



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- enhance iterative risk-based design
- desktop and web applications



apps.smartengineering.si

- web -> accessible, user friendly, manageable

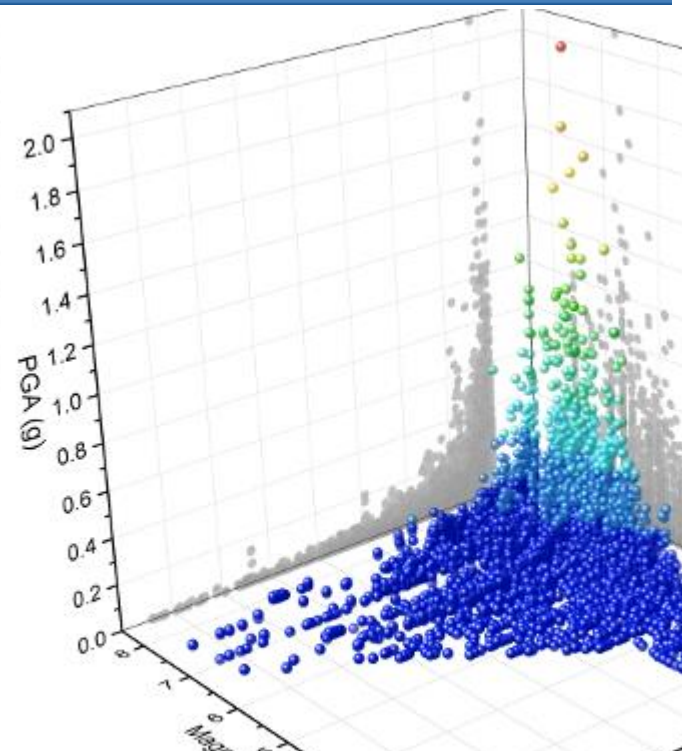
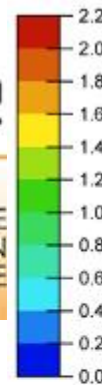
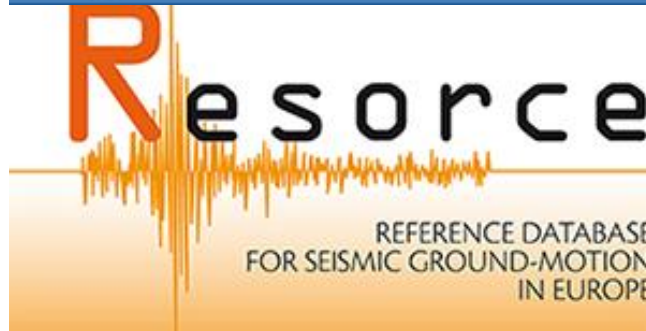
Software development



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Strong ground motion database

- PEER
- RESORCE



Total records: 9188
Unique records: 9030

More than 18000 horizontal ground motion components

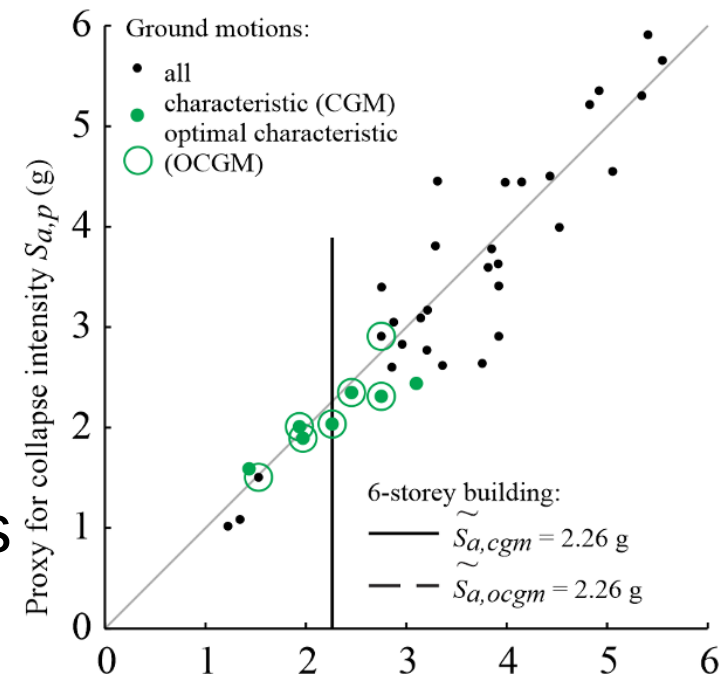


- CGM application
 - ▣ selection of so called **C**haracteristic **G**round **M**otions (3R method – Dolšek, Brozovič)
- Qfactor application
 - ▣ assessment of risk targeted design seismic intensity & behavior factor q
- Strong ground motion database application
 - ▣ interface (access, search, download)

CGMapp introduction

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- 3R method (Dolšek & Brozovič, 2016)
 - is collapse risk sufficient?
 - trivial decision model
 - characteristic ground motions
- Application
 - automate selection of CGMs



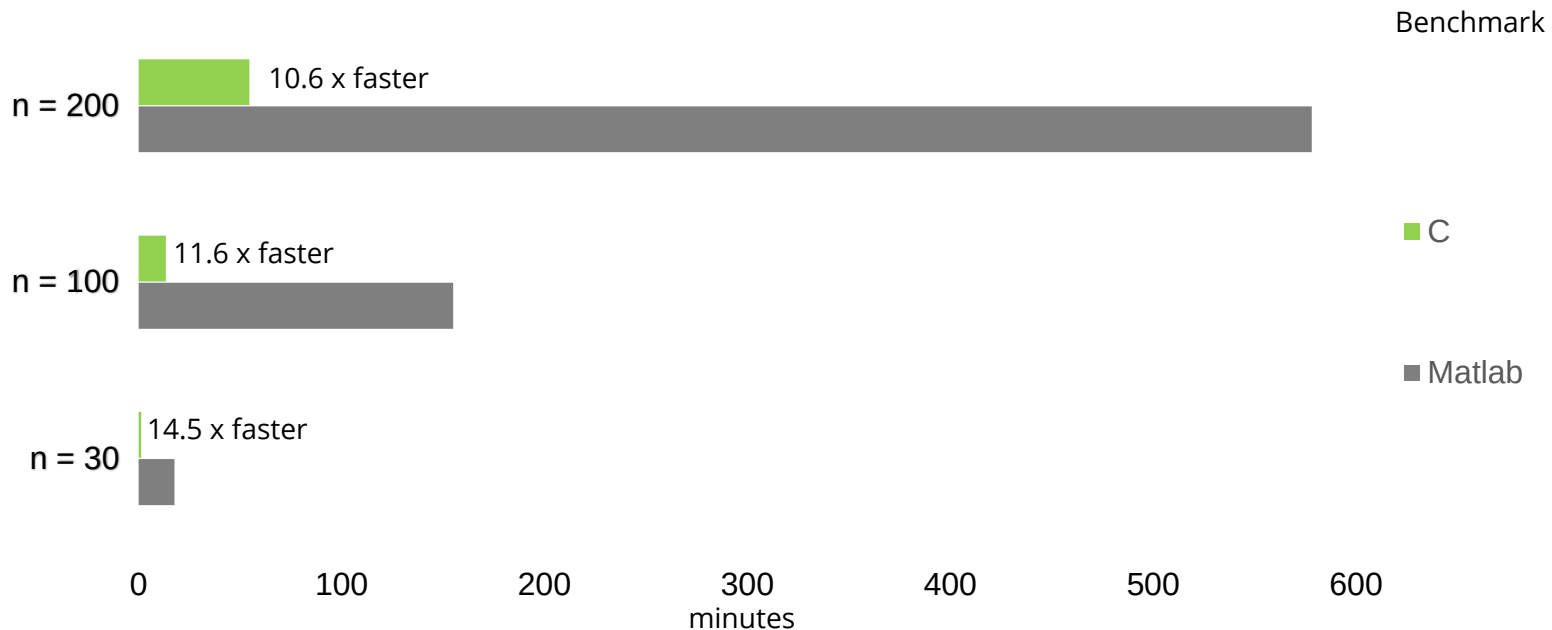
CGMapp

1.step: selection of hazard-consistent GMs



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- Conditional spectrum approach
Original algorithm (Jayaram et al. – MATLAB)
- Translated into C programming language



9030 records (~18000 spectra)

Ubuntu 12.04 64-bit (VM)
Matlab R2013a
Processor: Intel Core i7-3630QM CPU 2.400Hz x 4
Memory: 2.9GiB

General:

Select ground motions based on: i
 A: Single arbitrary horizontal ground motion compon... v

Number of GM i 30 v

Cond. period T^* (s) i 1 v

Ground motion prediction model:

Select ground motion prediction model i
 Campbell & Bozorgnia 2008 v

$V_{S,30}$ (m/s) i 400 v Z_{TOR} (km) i 0 v

δ (°) i 90 v λ (°) i 180 v Z_{VS} (km) i 2 v

Mean earthquake scenario:

Earthquake scenario defined by i
 M, R, $S_{a,ct}$ v

Define hazard function as: i
 User-defined v

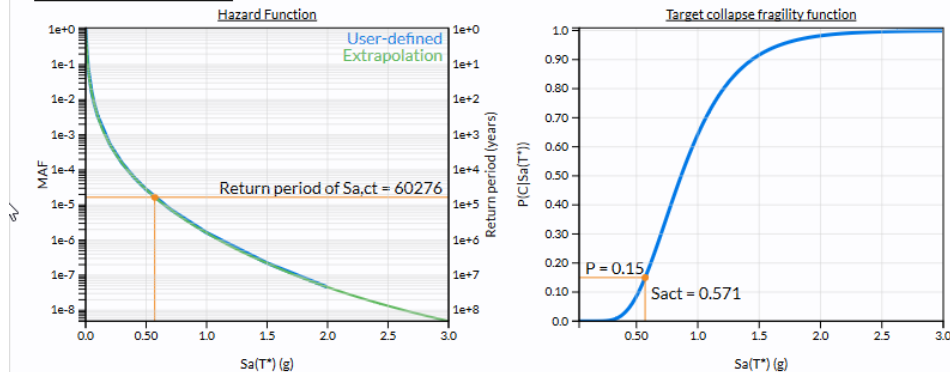
Characteristic value of target collapse intensity $S_{a,ct}$ is automatically calculated when all required fields are set: nGM, Hazard & Fragility function parameters

Hazard function:

	Acceleration (g)	MAF
1	0.0001	1.11
2	0.001	0.982
3	0.01	0.215
4	0.02	0.0833
5	0.05	0.0162
6	0.07	0.00787
7	0.1	0.00341
8	0.2	0.00054

Target collapse risk i β_t i
 0.00001 v 0.4 v

Clear hazard function table



Deaggregation

Magnitude M i 7.01 v Distance R (km) i 25.3 v $S_{a,ct}$ (g): i 0.571 v Parameter ϵ i 2.128 v

Magnitude

Min i v Max i v

Closest source-to-site distance

Min (km) i v Max (km) i v

Shear wave velocity V_{s30}

Min (m/s) i v Max (m/s) i v

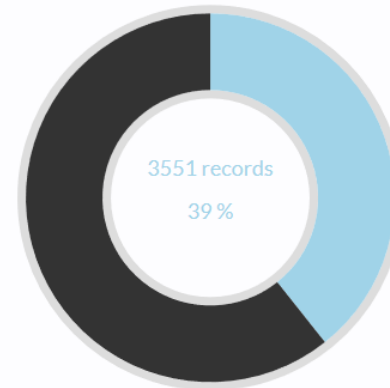
Select earthquake origin

All selected v

Select database source

PEER v

Number of potential records for selection



Advanced options

Scaling i $\checkmark$ 4 v useVar i compute v nPerTgt i 20 v

nLoop i 2 v penalty i 0 v Seed i 1 v

weight mean i 1 v weight sd i 2 v

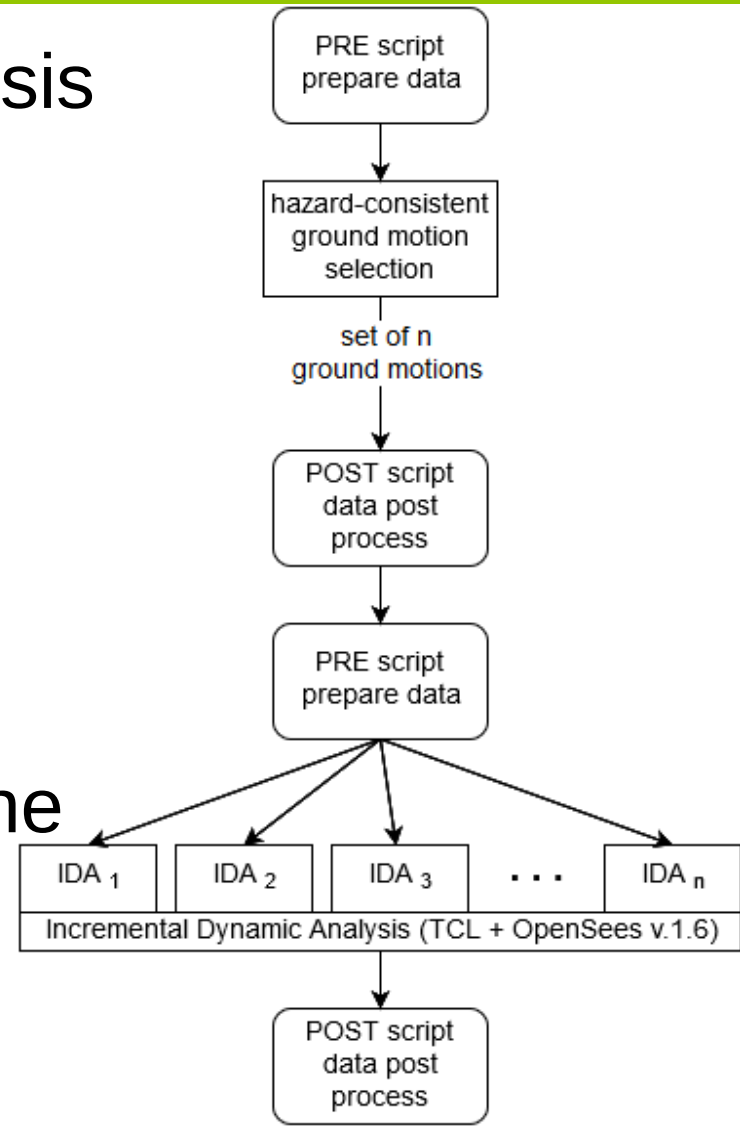
CGMapp

2. step: Incremental Dynamic Analysis



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- Nonlinear dynamic analysis of SDOF model
- Requirement: SDOF on the basis of pushover analysis
- OpenSees -> IDA
- Distributed workload on the computer cluster



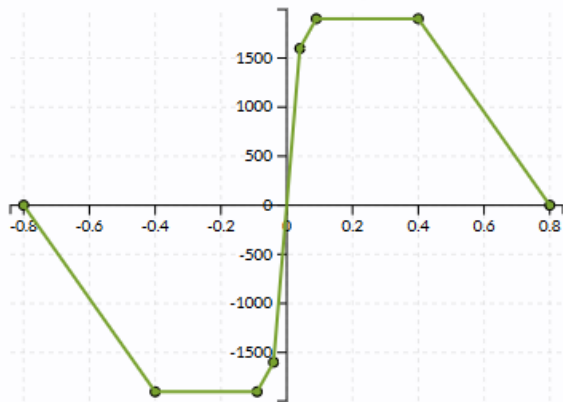


Data for SDOF model

Mass & Damping

Mass (t) α_M β_K β_{Kinit} β_{Kcomm}
 1000 0.63 0 0 0

Material envelope



Displacement (m)

Material

TakedaDAsym

Envelope type

☒ Symmetrical ☐ Non-symmetrical

Positive envelope points:

F1p (kN) F2p (kN) F3p (kN) F4p (kN)
 1600 1900 1900 0.1
 D1p (m) D2p (m) D3p (m) D4p (m)
 0.04 0.09 0.4 0.8

Period of SDOF model in positive direction (s) 0.993

Other envelope data:

Beta
 0.8

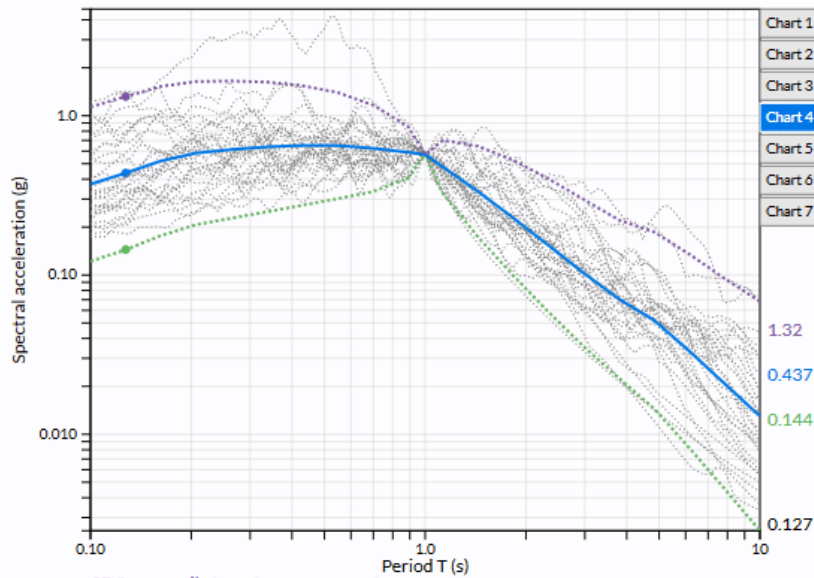
IDA options

nPoints tInteg (s)
 30 0.005
 dPGA_g (g) dPGA_c (g)
 0.05 0.01

Trim ground motions
☐ SaTol Sa tolerance PGATol PGA tolerance

Results

Response spectra of selected ground motions

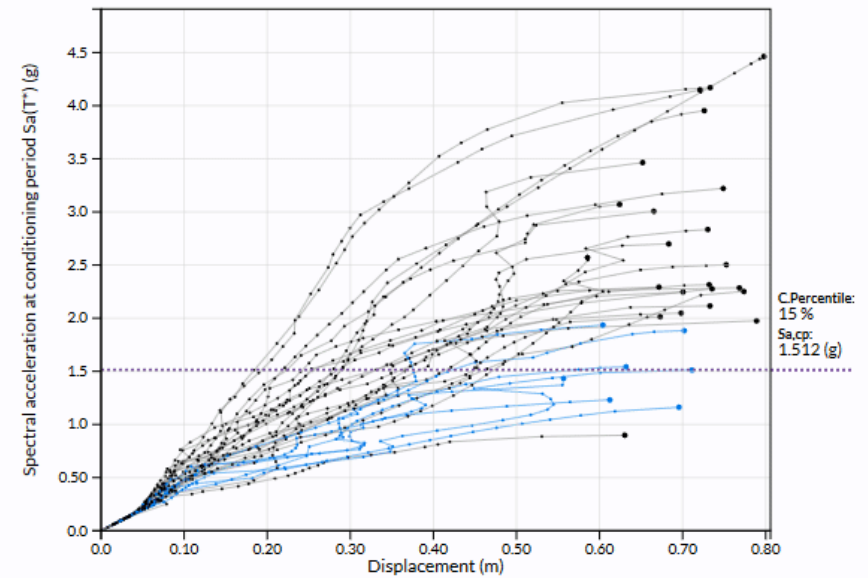


97.5 percentile target response spectrum
Median target response spectrum
2.5 percentile target response spectrum

Earthquake epicentre locations

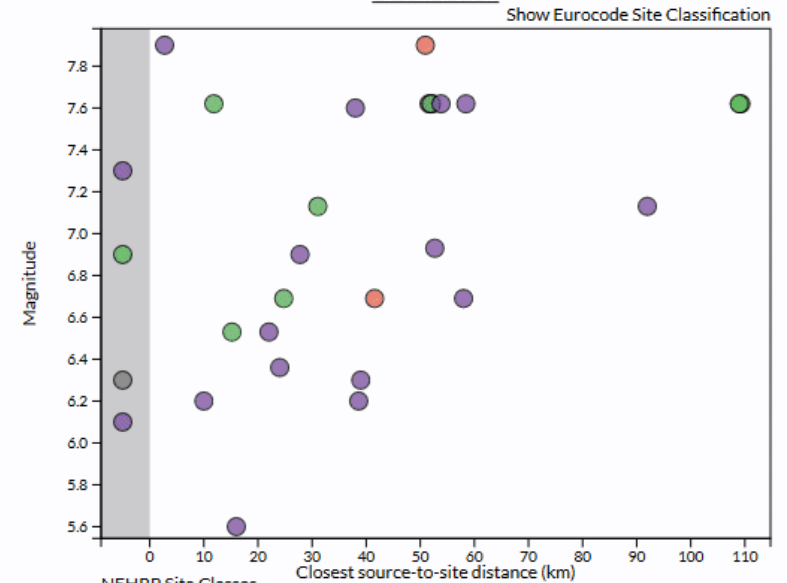


IDA curves for SDOF model



IDA curves of characteristic ground motions
IDA curves of other hazard-consistent ground motions

Distribution



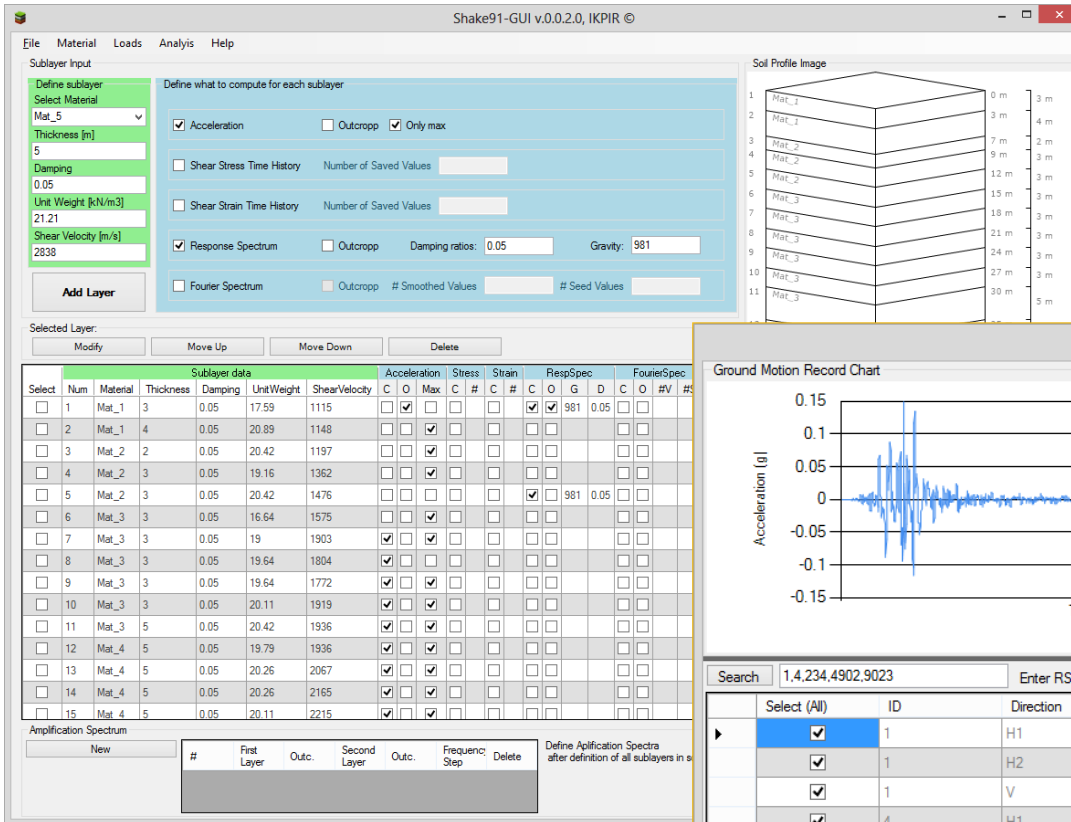
NEHRP Site Classes
A: $V_{s30} > 1524$ m/s
B: $762 \text{ m/s} < V_{s30} < 1524$ m/s
C: $366 \text{ m/s} < V_{s30} < 762$ m/s
D: $183 \text{ m/s} < V_{s30} < 366$ m/s

Strong Ground Motion Database

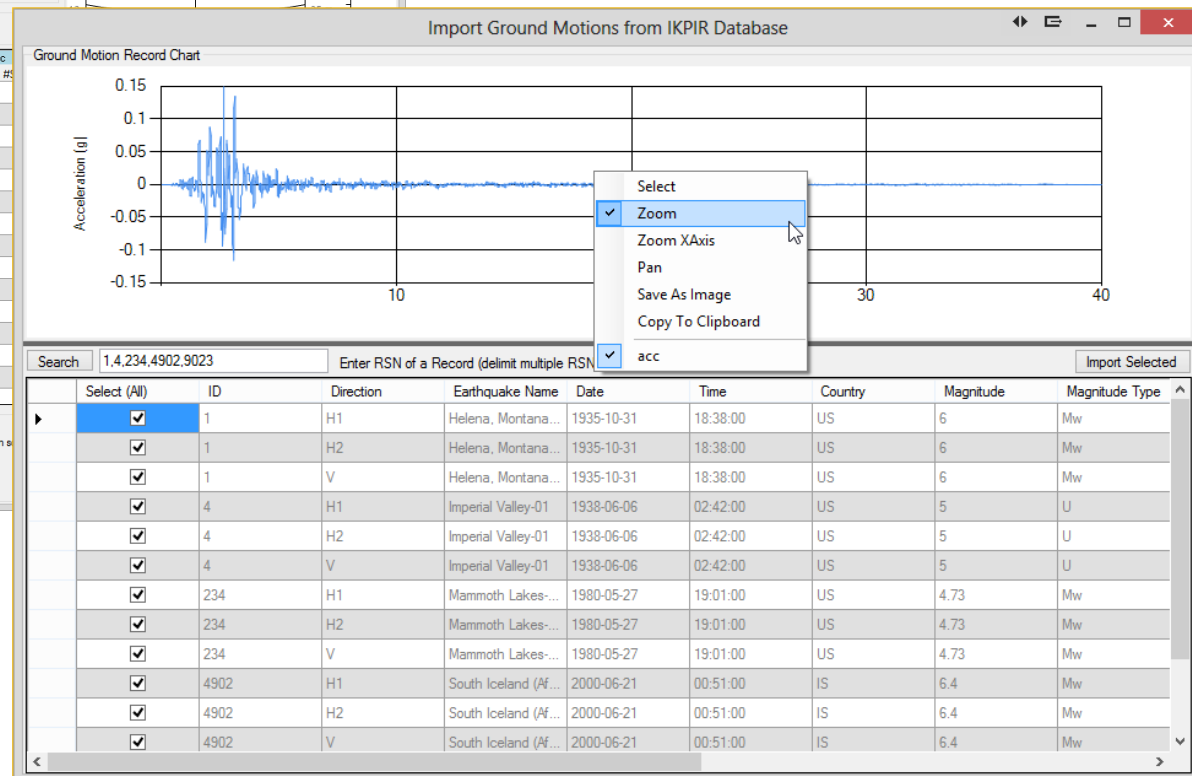
public API (example usage)



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Graphical user interface for
Shake91 (Idriss & Sun)



equivalent linear seismic
response
analysis of horizontally layered
soil deposits

Thank you for your attention

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□ Publications:

- Dolšek M, Brozovič M. Seismic response analysis using characteristic ground motion records for risk-based decision making. *Earthquake Engineering and Structural Dynamics* 2016; 45(3):401–420.
- Lazar Sinković N, Brozovič M, Dolšek M. Risk-based seismic design for collapse safety. *Earthquake Engineering and Structural Dynamics* 2016, 45: 1451–1471.
- Kosič M, Dolšek M, Fajfar P. Dispersions for the pushover-based risk assessment of reinforced concrete frames and cantilever walls. *Earthquake Engineering and Structural Dynamics* 2016; doi: 10.1002/eqe.2753.
- Žižmond J, Dolšek M. Risk-targeted force-based design and performance check by means of nonlinear analysis. In: Tenth Pacific Conference on Earthquake Engineering, 6-8 November 2015, Sydney, Australia. Building an Earthquake Resilient Pacific. Sydney: Australian